

IMSE Conference 2018

Tensor-product interpolation for high-dimensional integrals

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High-dimensional integrals

- Generalised Gaussian integrals in mathematical finance

$$\int_{\mathbb{R}^d} f(\mathbf{x}) e^{-\frac{1}{2}\mathbf{x}^T A \mathbf{x}} d\mathbf{x}$$

- Ising integrals in mathematical physics

$$\int_{[0,1]^{d-1}} \left(\prod_{j \leq k} \frac{t_k t_{k-1} \cdots t_{j+1} - 1}{t_k t_{k-1} \cdots t_{j+1} + 1} \right)^2 dt$$

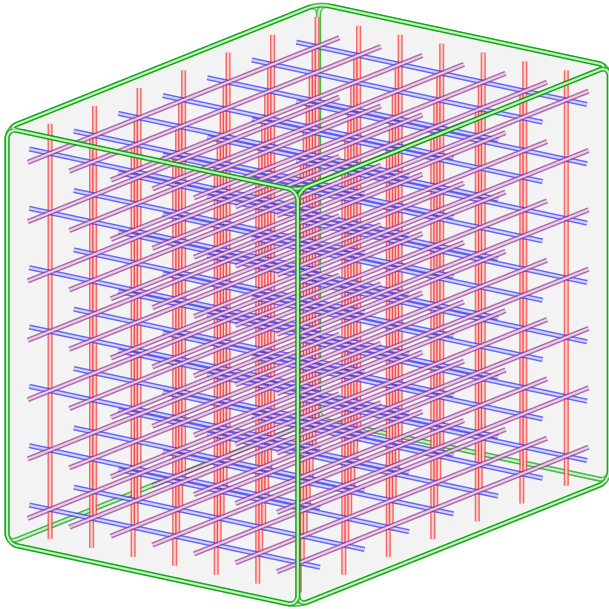
- Weyl's integrals in representation theory / random matrix theory

$$\int_{\mathbb{U}_d} f(\mathbf{U}) d\mathbf{U} = \frac{1}{(2\pi)^d d!} \int_{[0,2\pi]^d} f(\text{diag}(e^{i\theta_1}, \dots, e^{i\theta_d})) \prod_{j \leq k} |e^{i\theta_j} - e^{i\theta_k}|^2 d\theta$$

- Stochastic PDEs

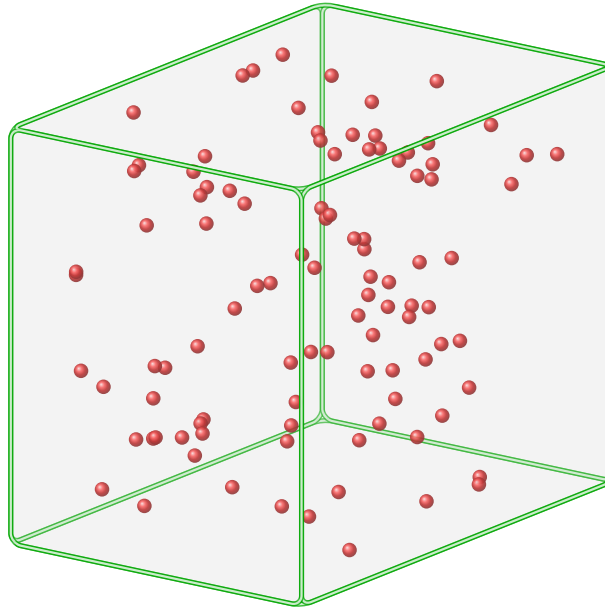
$$\mathcal{D}_x(\xi) u(x, \xi) = f(x)$$

Main message



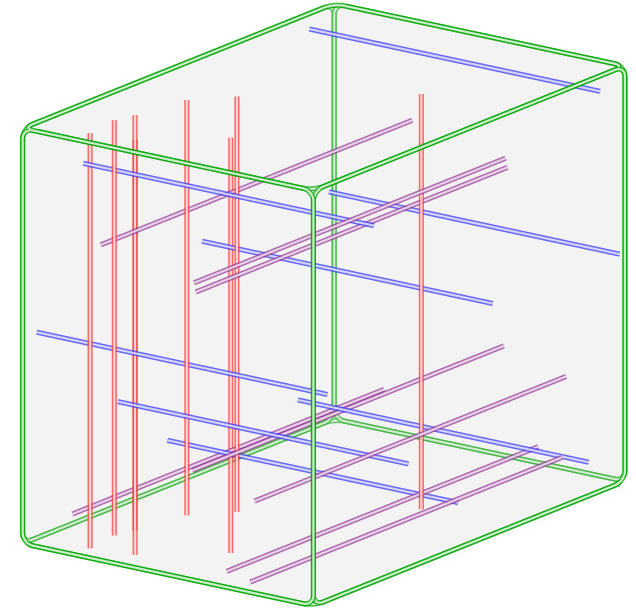
full grid

bad



Monte-Carlo

good



cross interpolation

better

Outline

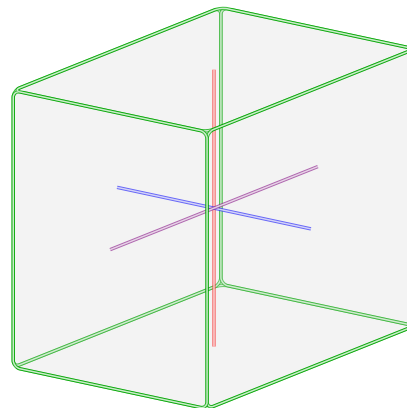
- Introduction
- Cross interpolation theory
 - ⇒ Functions
 - Matrices
 - Tensors
- Cross interpolation practice

Cross interpolation (for functions)

$$\begin{aligned}\int_{\mathbb{R}^3} e^{-\frac{1}{2}\|\mathbf{x}\|^2} d\mathbf{x} &= \int_{\mathbb{R}} \int_{\mathbb{R}} \int_{\mathbb{R}} e^{-\frac{1}{2}(x_1^2+x_2^2+x_3^2)} dx_1 dx_2 dx_3 \\ &= \left(\int_{\mathbb{R}} e^{-\frac{1}{2}x_1^2} dx_1 \right) \left(\int_{\mathbb{R}} e^{-\frac{1}{2}x_2^2} dx_2 \right) \left(\int_{\mathbb{R}} e^{-\frac{1}{2}x_3^2} dx_3 \right) \\ &= \left(\sqrt{2\pi} \right)^3\end{aligned}$$

Separation of variables

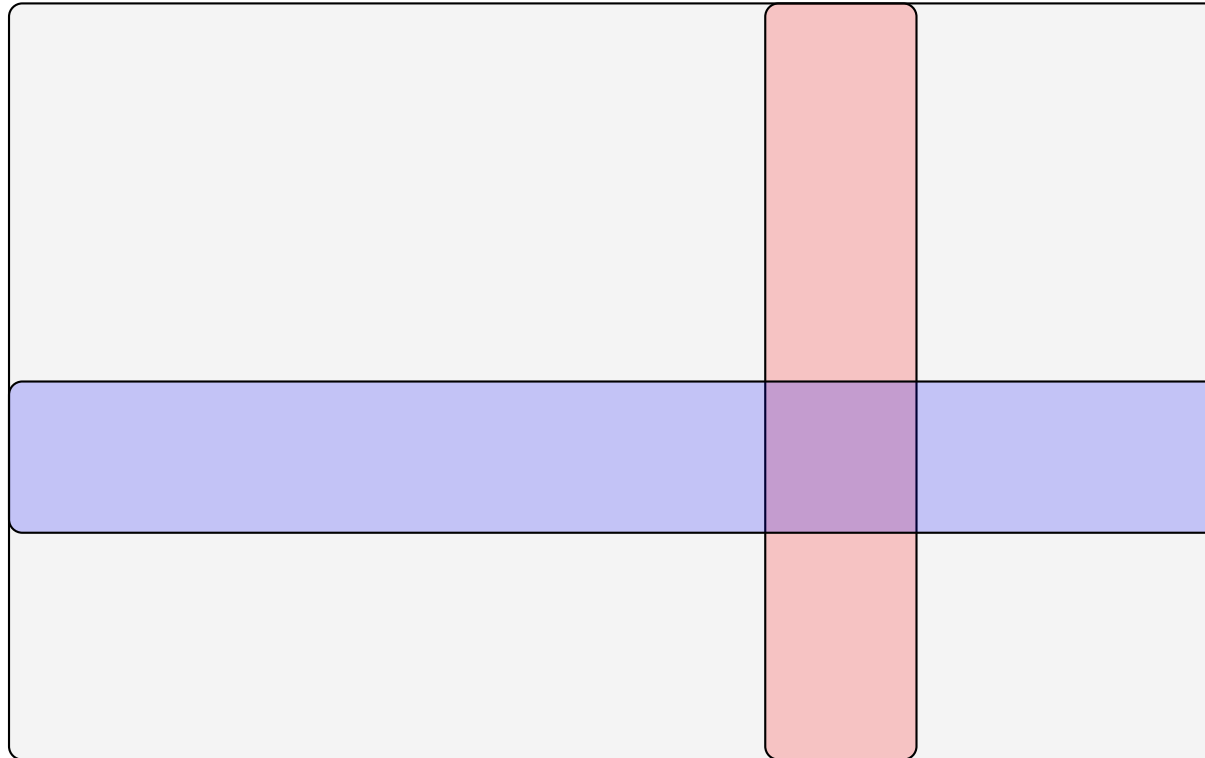
$$\begin{aligned}e^{-\frac{1}{2}(x_1^2+x_2^2+x_3^2)} &= e^{-\frac{1}{2}x_1^2} e^{-\frac{1}{2}x_2^2} e^{-\frac{1}{2}x_3^2} \\ f(x_1, x_2, x_3) &= f(x_1, 0, 0)f(0, x_2, 0)f(0, 0, x_3)\end{aligned}$$



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Cross interpolation (for matrices)



$$A(i, j) \approx \tilde{A}(i, j) = \mathbf{A}(i, \mathcal{J}) [\mathbf{A}(\mathcal{J}, \mathcal{J})]^{-1} \mathbf{A}(\mathcal{J}, j).$$

$mr + rn - r^2$ parameters (SVD), $mr + rn - r^2$ interpolation points

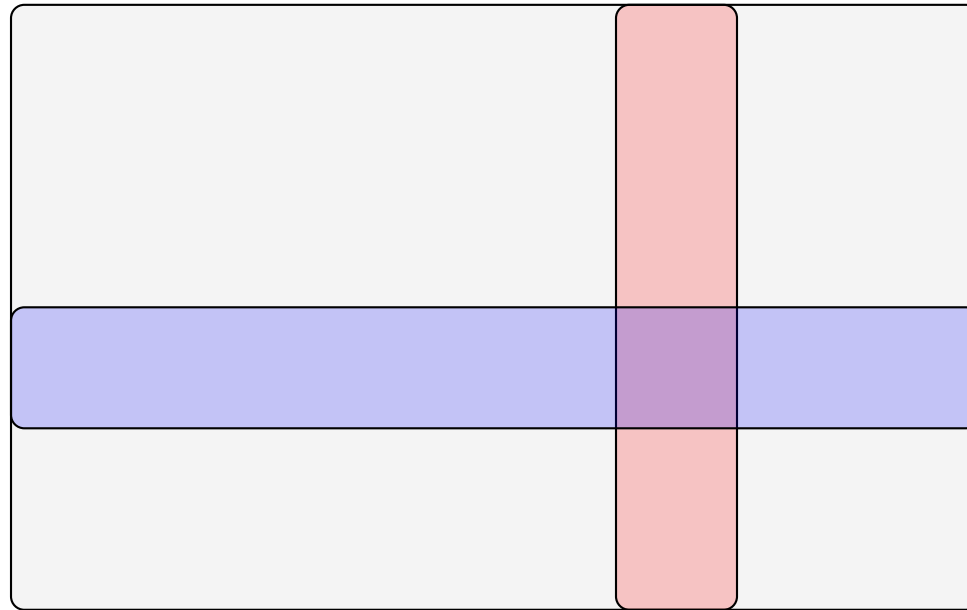
Interpolation (good)

$$\begin{aligned}
 \mathbf{A} &= \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \\ 1/4 & 1/5 & 1/6 & 1/7 & 1/8 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &= \begin{pmatrix} 1/2 & 1/3 \\ 1/3 & 1/4 \\ 1/4 & 1/5 \\ 1/5 & 1/6 \\ 1/6 & 1/7 \end{pmatrix} \cdot \begin{pmatrix} 1/2 & 1/3 \\ 1/3 & 1/4 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \end{pmatrix} \\
 &+ \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1.67 & 2.86 & 3.57 \\ 0 & 0 & 2.86 & 5.00 & 6.35 \\ 0 & 0 & 3.57 & 6.35 & \mathbf{8.17} \end{pmatrix} \times \mathbf{10}^{-3}
 \end{aligned}$$

Interpolation (not so good)

$$\begin{aligned}
 \mathbf{A} &= \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \\ 1/4 & 1/5 & 1/6 & 1/7 & 1/8 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &= \begin{pmatrix} 1/5 & 1/6 \\ 1/6 & 1/7 \\ 1/7 & 1/8 \\ 1/8 & 1/9 \\ 1/9 & 1/10 \end{pmatrix} \cdot \begin{pmatrix} 1/8 & 1/9 \\ 1/9 & 1/10 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &+ \begin{pmatrix} \mathbf{8.00} & 1.90 & 0.36 & 0 & 0 \\ 1.90 & 0.51 & 0.10 & 0 & 0 \\ 0.36 & 0.10 & 0.02 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix} \times \mathbf{10}^{-2}
 \end{aligned}$$

Quasioptimality [Goreinov, Tyrtyshnikov, 2001 & 2011]



$$[\mathcal{I}, \mathcal{J}] = \text{maxvol}[A(i, j)], \quad \tilde{A}(i, j) = A(i, \mathcal{J}) [A(\mathcal{J}, \mathcal{J})]^{-1} A(\mathcal{J}, j).$$

$$\|A - \tilde{A}\| \leq (r + 1) \min_{\text{rank } X=r} \|A - X\|$$

$$|A - \tilde{A}| \leq (r + 1)^2 \min_{\text{rank } X=r} |A - X|$$

Interpolation (maximum-volume)

$$\begin{aligned}
 \mathbf{A} &= \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \\ 1/4 & 1/5 & 1/6 & 1/7 & 1/8 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &= \begin{pmatrix} 1/2 & 1/5 \\ 1/3 & 1/6 \\ 1/4 & 1/7 \\ 1/5 & 1/8 \\ 1/6 & 1/9 \end{pmatrix} \cdot \begin{pmatrix} 1/2 & 1/5 \\ 1/5 & 1/8 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \end{pmatrix} \\
 &+ \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & \mathbf{3.09} & 1.59 & 0 & -1.18 \\ 0 & 1.59 & 0.85 & 0 & -0.66 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & -1.18 & -0.66 & 0 & 0.55 \end{pmatrix} \times \mathbf{10}^{-3}
 \end{aligned}$$

Interpolation (cross algorithm, step I)

$$\begin{aligned}
 \mathbf{A} &= \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \\ 1/4 & 1/5 & 1/6 & 1/7 & 1/8 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &= \begin{pmatrix} 1/2 \\ 1/3 \\ 1/4 \\ 1/5 \\ 1/6 \end{pmatrix} \cdot \left(\frac{1}{2} \right)^{-1} \cdot \left(\frac{1}{2} \quad \frac{1}{3} \quad \frac{1}{4} \quad \frac{1}{5} \quad \frac{1}{6} \right) \\
 &= \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 2.78 & 3.33 & 3.33 & 3.17 \\ 0 & 3.33 & 4.17 & 4.28 & 4.17 \\ 0 & 3.33 & 4.28 & \mathbf{4.50} & 4.44 \\ 0 & 3.17 & 4.17 & 4.44 & 4.44 \end{pmatrix} \times 10^{-2}
 \end{aligned}$$

Interpolation (cross algorithm, step 2)

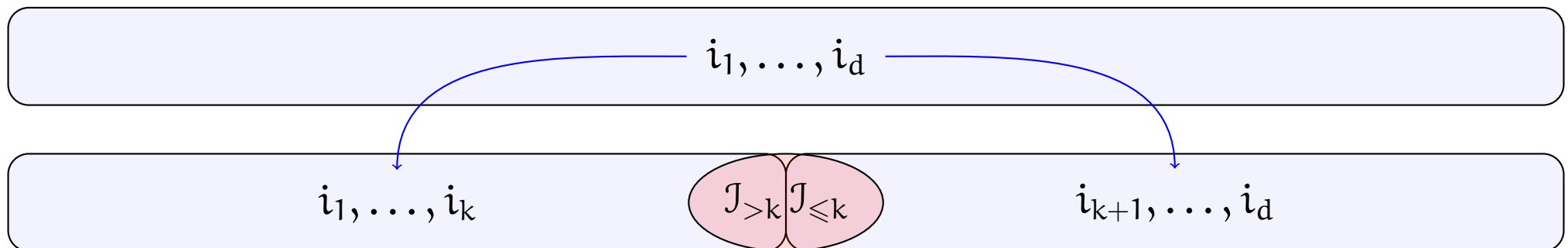
$$\begin{aligned}
 \mathbf{A} &= \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/3 & 1/4 & 1/5 & 1/6 & 1/7 \\ 1/4 & 1/5 & 1/6 & 1/7 & 1/8 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \\ 1/6 & 1/7 & 1/8 & 1/9 & 1/10 \end{pmatrix} \\
 &= \begin{pmatrix} 1/2 & 1/5 \\ 1/3 & 1/6 \\ 1/4 & 1/7 \\ 1/5 & 1/8 \\ 1/6 & 1/9 \end{pmatrix} \cdot \begin{pmatrix} 1/2 & 1/5 \\ 1/5 & 1/8 \end{pmatrix}^{-1} \cdot \begin{pmatrix} 1/2 & 1/3 & 1/4 & 1/5 & 1/6 \\ 1/5 & 1/6 & 1/7 & 1/8 & 1/9 \end{pmatrix} \\
 &+ \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & \mathbf{3.09} & 1.59 & 0 & -1.18 \\ 0 & 1.59 & 0.85 & 0 & -0.66 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & -1.18 & -0.66 & 0 & 0.55 \end{pmatrix} \times \mathbf{10^{-3}}
 \end{aligned}$$

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Matrix formula for tensor case

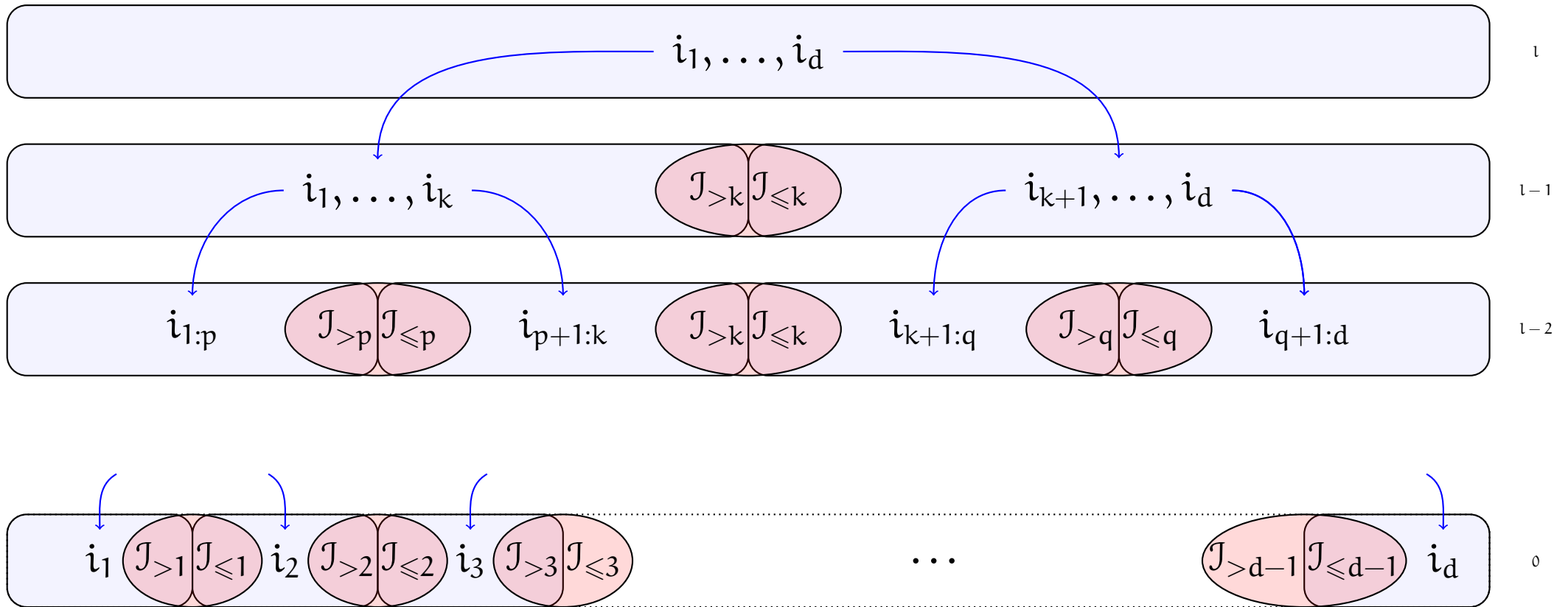
$$\begin{aligned}
\mathbf{A}(\mathbf{i}_1, \dots, \mathbf{i}_k; \mathbf{i}_{k+1}, \dots, \mathbf{i}_d) &= \mathbf{A}(\mathbf{i}_{\leq k}, \mathbf{i}_{> k}) \approx \tilde{\mathbf{A}}(\mathbf{i}_{\leq k}, \mathbf{i}_{> k}) \\
&= \mathbf{A}(\mathbf{i}_{\leq k}, \mathcal{J}_{> k}) [\mathbf{A}(\mathcal{J}_{\leq k}, \mathcal{J}_{> k})]^{-1} \mathbf{A}(\mathcal{J}_{\leq k}, \mathbf{i}_{> k}) \\
&= \mathbf{A}(\mathbf{i}_1 \dots \mathbf{i}_k, \mathcal{J}_{> k}) [\mathbf{A}(\mathcal{J}_{\leq k}, \mathcal{J}_{> k})]^{-1} \mathbf{A}(\mathcal{J}_{\leq k}, \mathbf{i}_{k+1} \dots \mathbf{i}_d)
\end{aligned}$$



Error estimate

$$|\mathbf{A} - \tilde{\mathbf{A}}| \leq (r_k + 1)^2 \min |\mathbf{A} - \mathbf{X}|$$

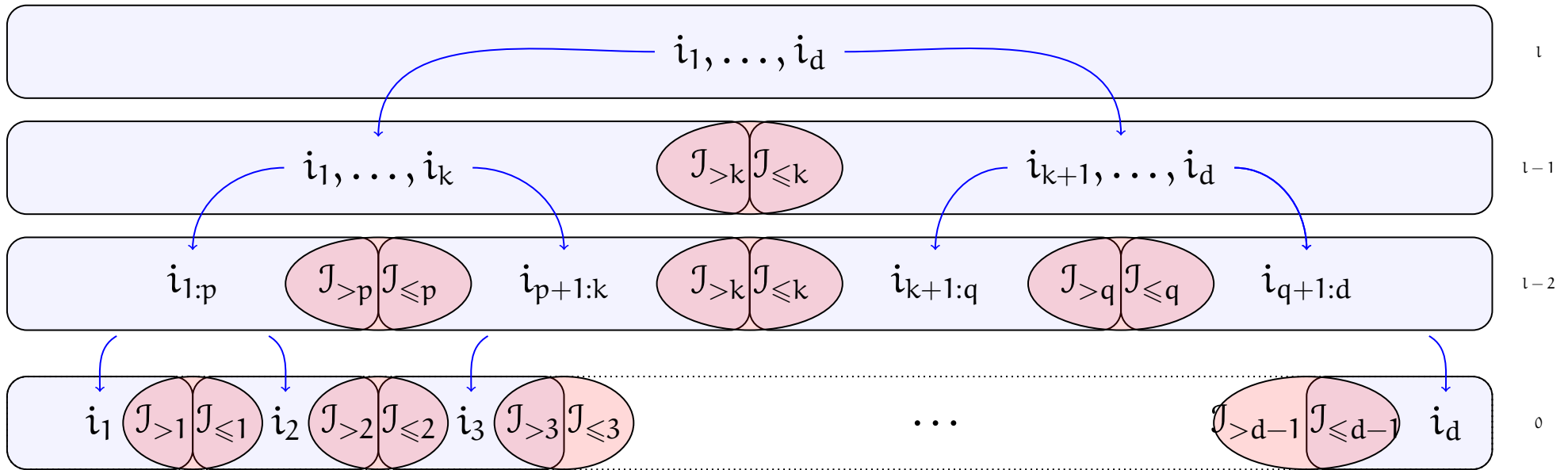
Separation of variables on a dimension tree



TT-cross interpolation formula [Oseledets, Tyrtyshnikov, 2010]

$$\tilde{A}(i_1, i_2, \dots, i_d) = A(i_1, \mathcal{J}_{>1}) [A(\mathcal{J}_{\leq 1}, \mathcal{J}_{>1})]^{-1} A(\mathcal{J}_{\leq 1}, i_2, \mathcal{J}_{>2}) [A(\mathcal{J}_{\leq 2}, \mathcal{J}_{>2})]^{-1} \dots A(\mathcal{J}_{\leq d-1}, i_d)$$

Theorem (Quasioptimality) [Savostyanov, LAA 2014]

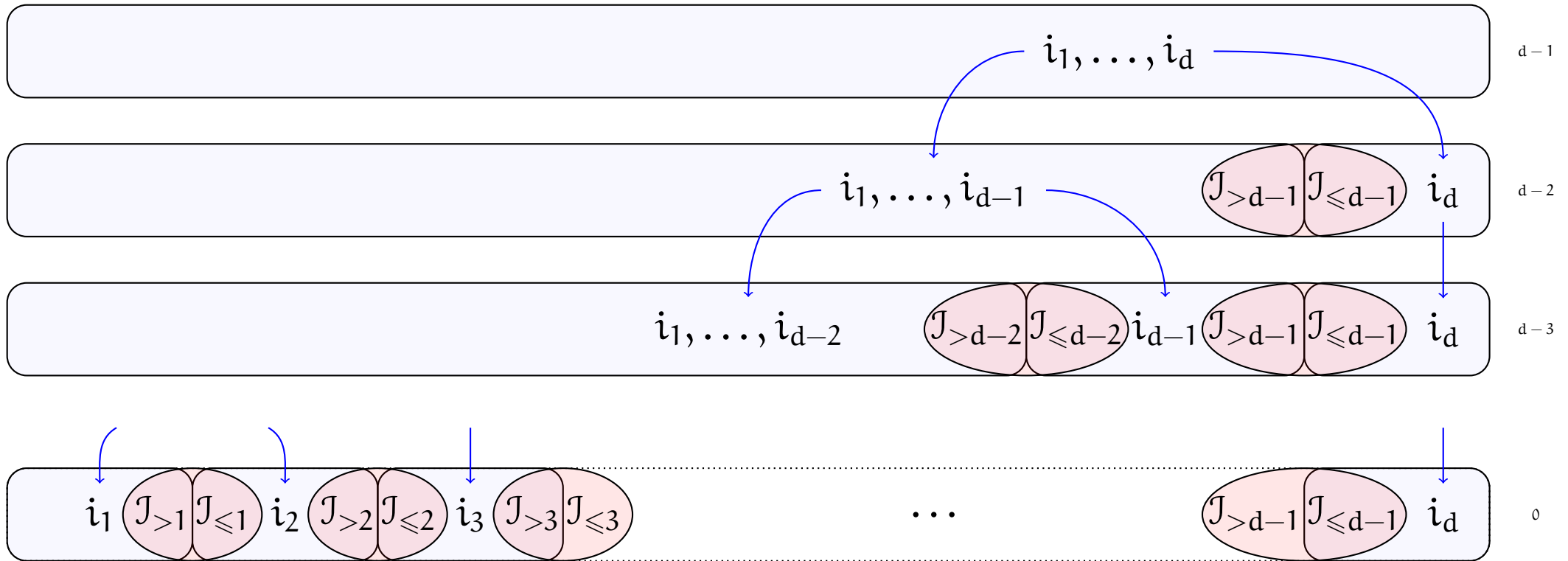


If $[J_{\leq k}, J_{> k}] = \maxvol[A(i_{\leq k}, i_{> k})]$ then

$$|A - \tilde{A}| \leq (2r + \kappa r + 1)^{\lceil \log_2 d \rceil} (r + 1)^2 |A - \tilde{A}_{\text{best}}|$$

$$r = \max r_k, \quad \kappa = \max \kappa_k, \quad \kappa_k = r_k |A| |A_k^{-1}|$$

Theorem (Interpolation) [Savostyanov, LAA 2014]



If indices are nested

$$i_{>k} \in \mathcal{J}_{>k} \Rightarrow i_{>k+1} \in \mathcal{J}_{>k+1}, \quad i_{\leq k} \in \mathcal{J}_{\leq k} \Rightarrow i_{\leq k-1} \in \mathcal{J}_{\leq k-1},$$

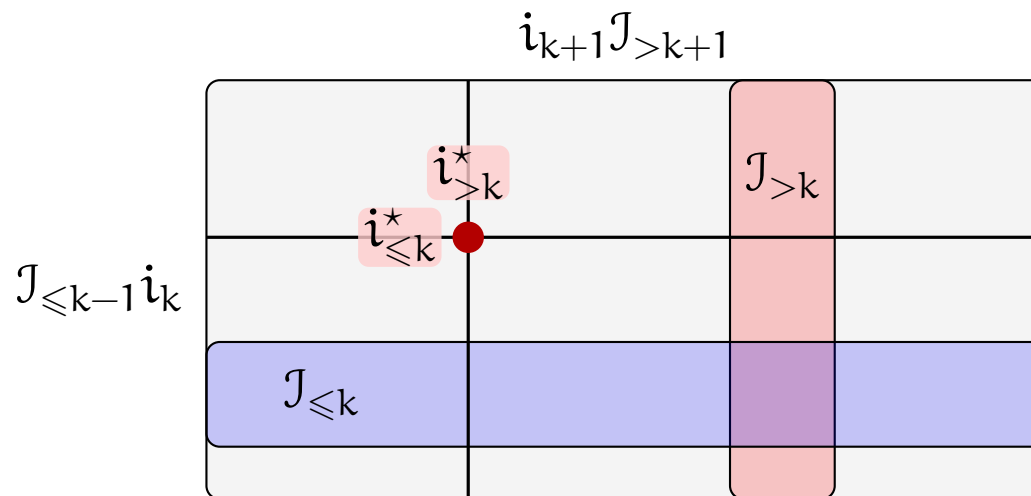
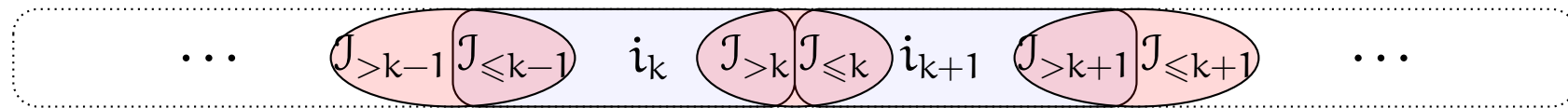
then interpolation formula interpolates in all points

$$A(\mathcal{J}_{\leq k-1}, i_k, \mathcal{J}_{>k}) = \tilde{A}(\mathcal{J}_{\leq k-1}, i_k, \mathcal{J}_{>k}), \quad k = 1, \dots, d.$$

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DMRG-like restricted greedy interpolation [Savostyanov, LAA 2014]

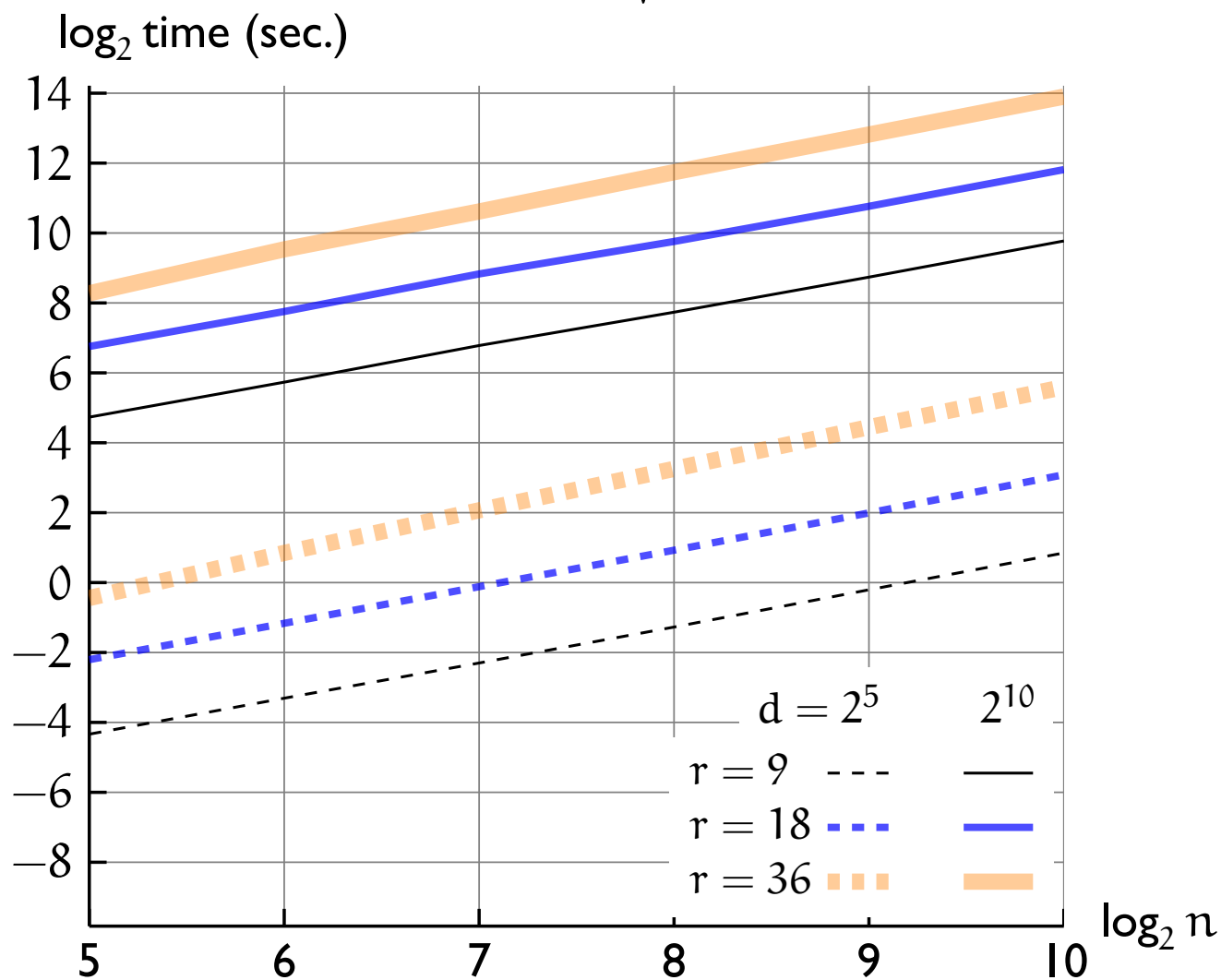


do $k = 1, \dots, d - 1$ (half-sweep)

- Find a pivot $i^* = (i_1^*, \dots, i_d^*)$ in $[A(J_{\leq k-1} i_k, i_{k+1} J_{>k+1})]$
- Add $i_{\leq k}^*$ to $J_{\leq k}$, and $i_{>k}^*$ to $J_{>k}$
- Update the TT-cores k and $k + 1$ of the interpolation \tilde{A}

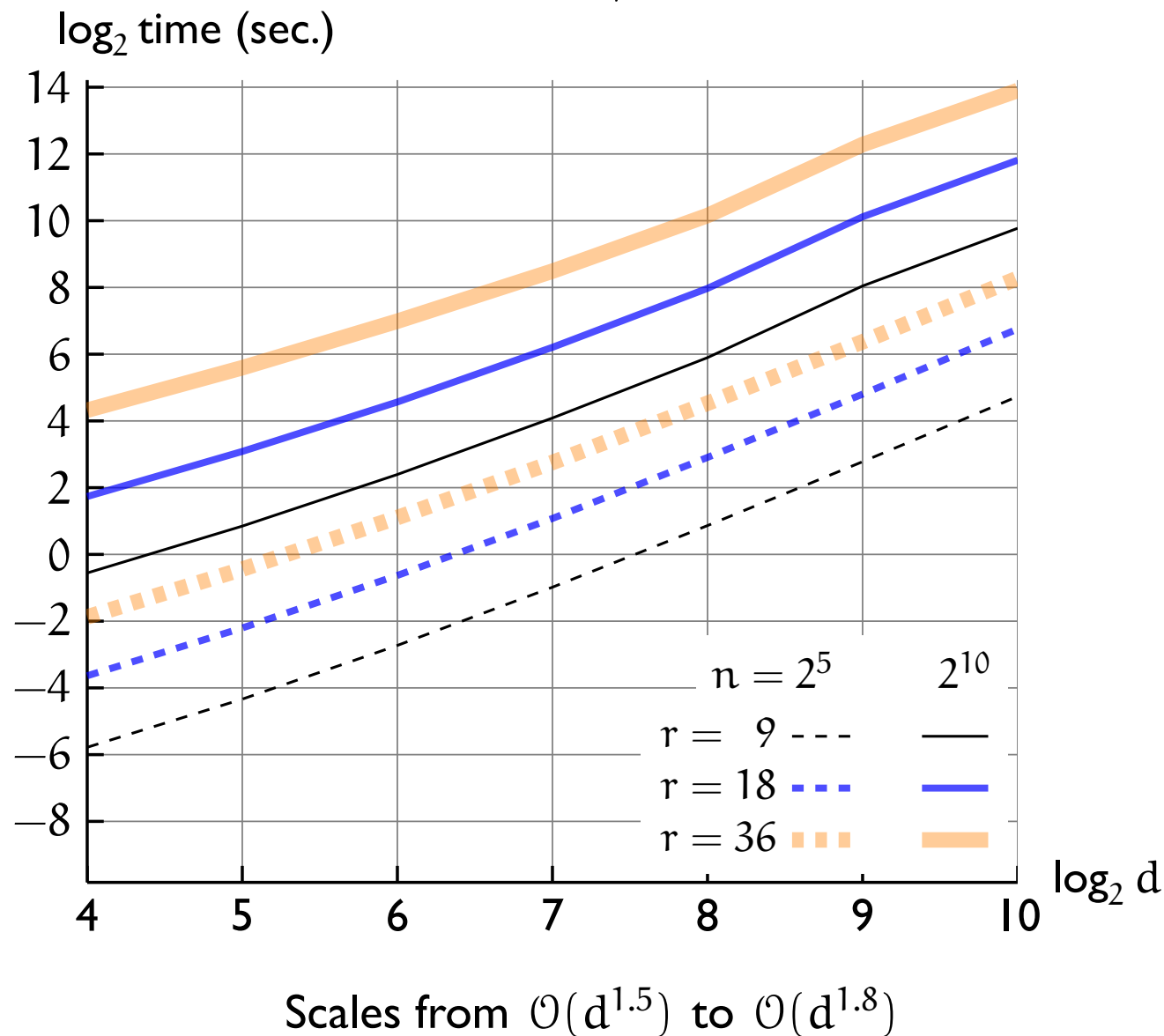
Complexity is $\sum_{k=1}^d r_{k-1} n_k r_k - \sum_{k=1}^{d-1} r_k$ tensor entries plus $\mathcal{O}(dnr^3)$ operations

Runtime wrt mode size for $A(i_1, \dots, i_d) = 1/\sqrt{i_1^2 + \dots + i_d^2}$



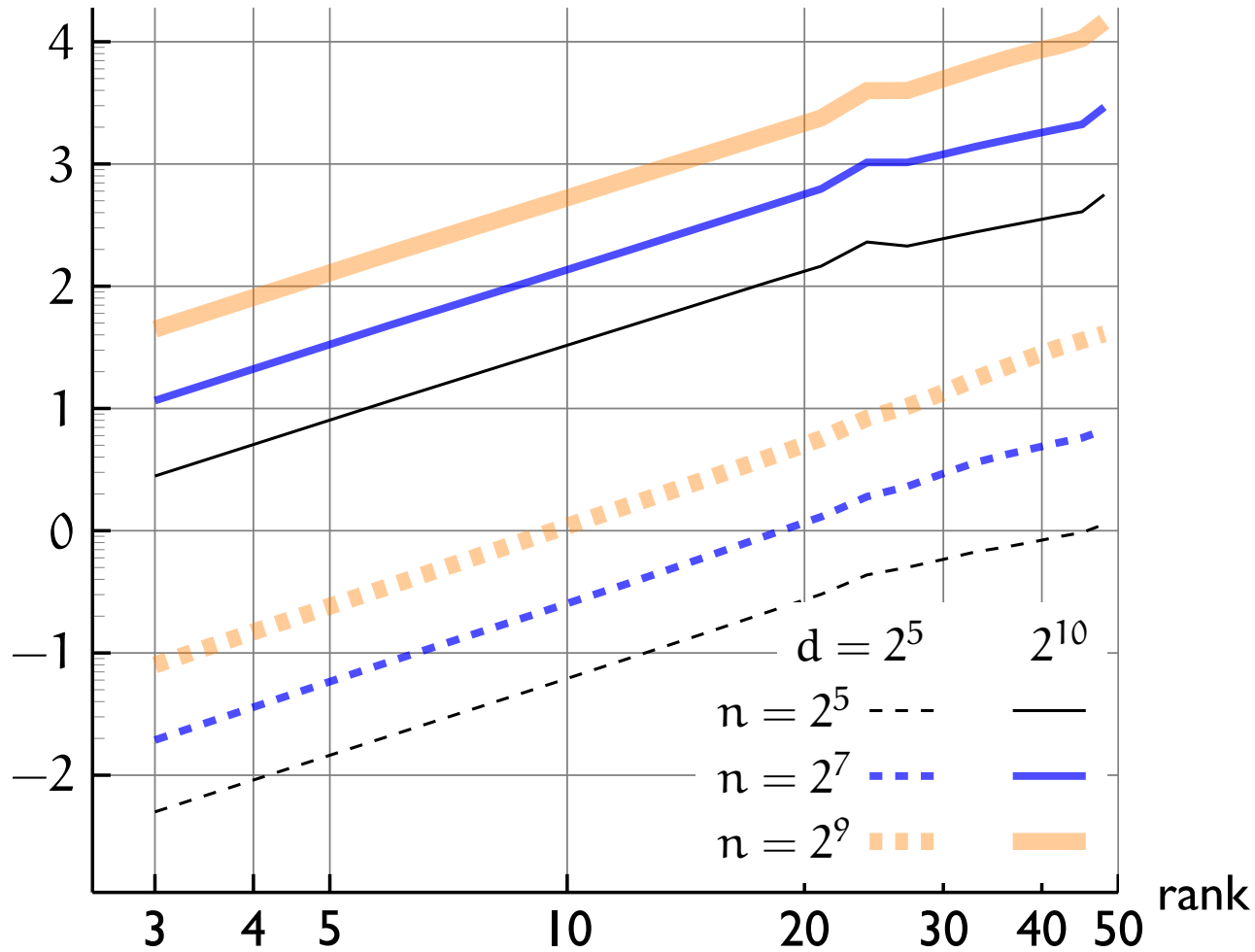
Strictly linear

Runtime wrt dimension for $A(i_1, \dots, i_d) = 1/\sqrt{i_1^2 + \dots + i_d^2}$



Runtime wrt rank for $A(i_1, \dots, i_d) = 1/\sqrt{i_1^2 + \dots + i_d^2}$

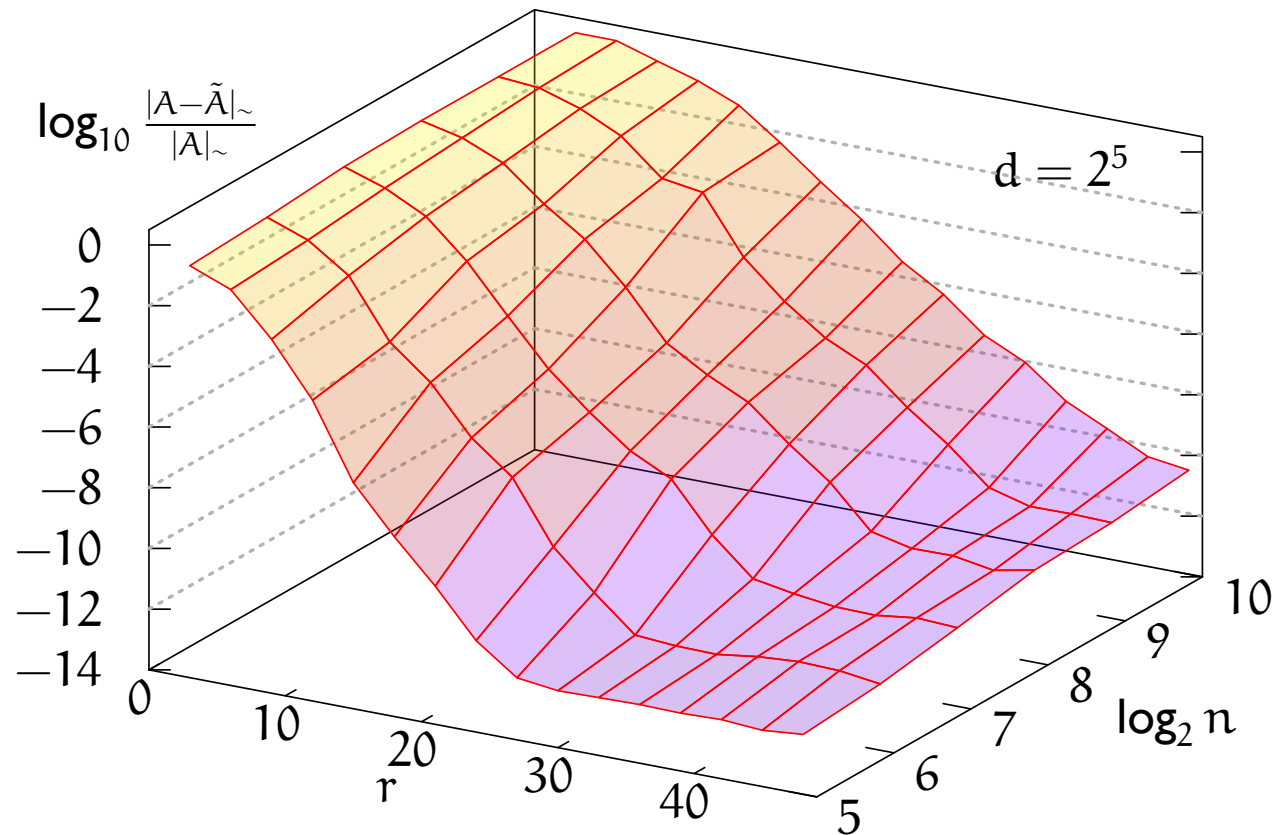
\log_{10} time (sec.)



Scales quadratically

Accuracy of interpolation

$$A(i_1, \dots, i_d) = (i_1^2 + \dots + i_d^2)^{-\frac{1}{2}}, \quad i_k = 1, \dots, n, \quad k = 1, \dots, d.$$



Reconstruct $n^d = (2^{10})^{32} = 2^{320} \approx 10^{100} = \text{googol}$ entries
 from $dnr^2 = 32 \cdot 2^{10} \cdot 50^2 \approx 8 \cdot 10^7$ samples = 1.2 GB of data

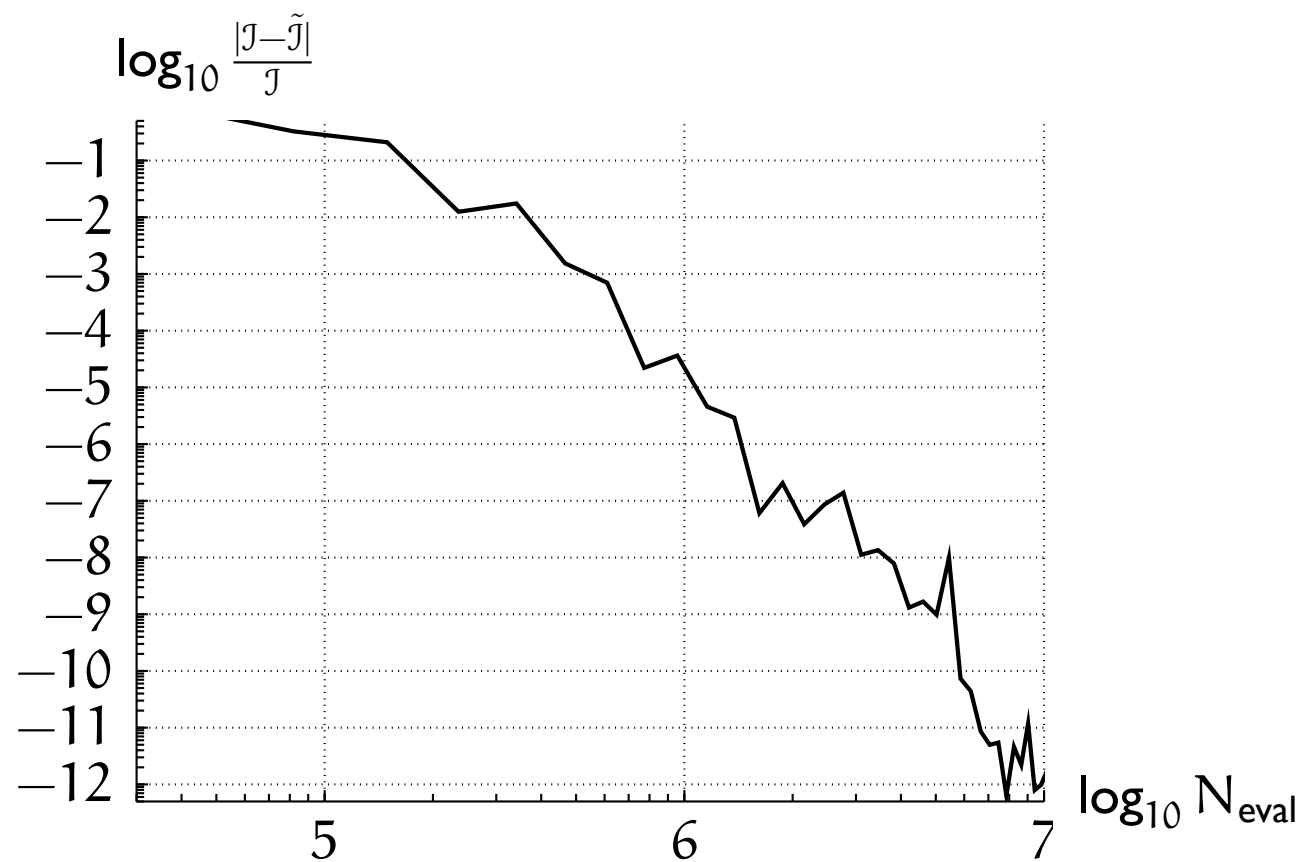
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Generalised Gaussian integral

$$\int_{\mathbb{R}^d} e^{-\frac{1}{2}\mathbf{x}^T \mathbf{A} \mathbf{x}} d\mathbf{x} = \frac{(2\pi)^{d/2}}{\sqrt{\det(\mathbf{A})}}$$

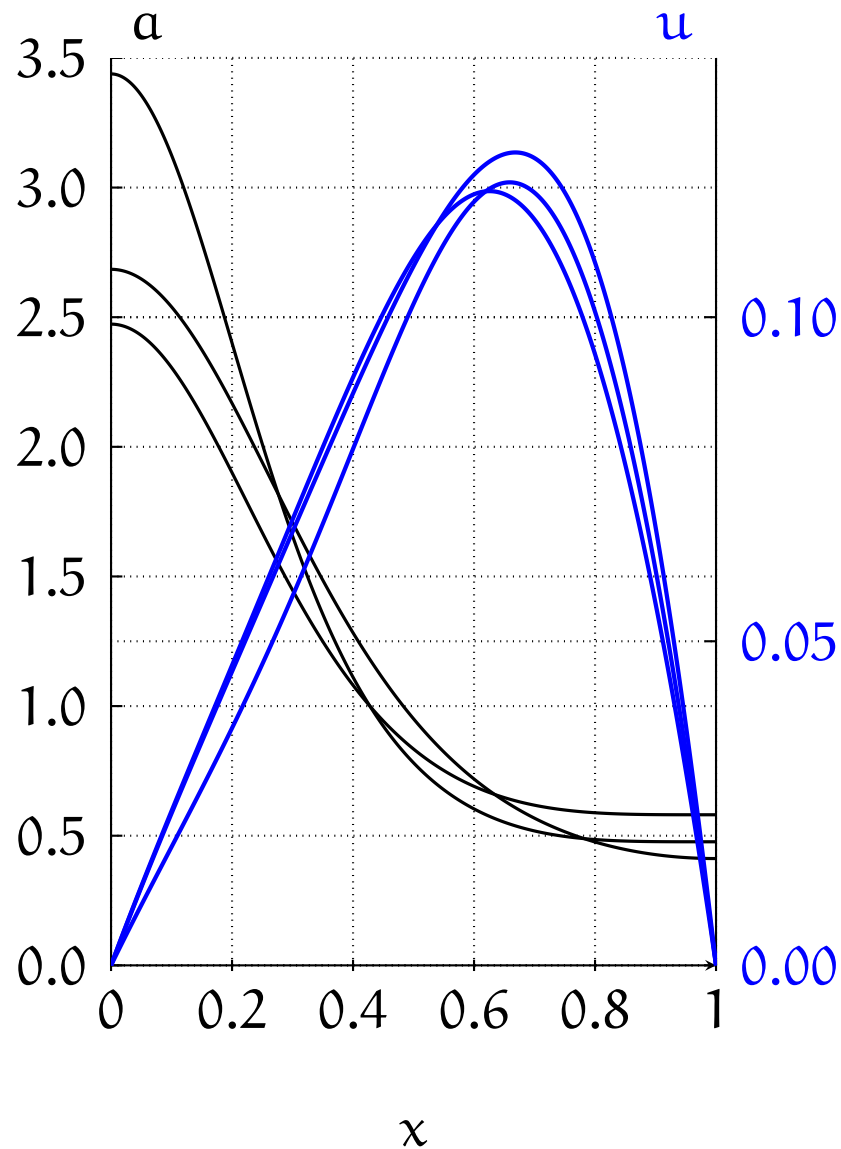
- $\mathbf{A} = [e^{-|i-j|}]_{i,j=1}^d$, $d = 100$, $n = 50$ nodes in each mode
- $n^d = 50^{100}$ quadrature nodes overall — **curse of dimensionality**



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Stochastic PDE



Karhunen-Loève expansion

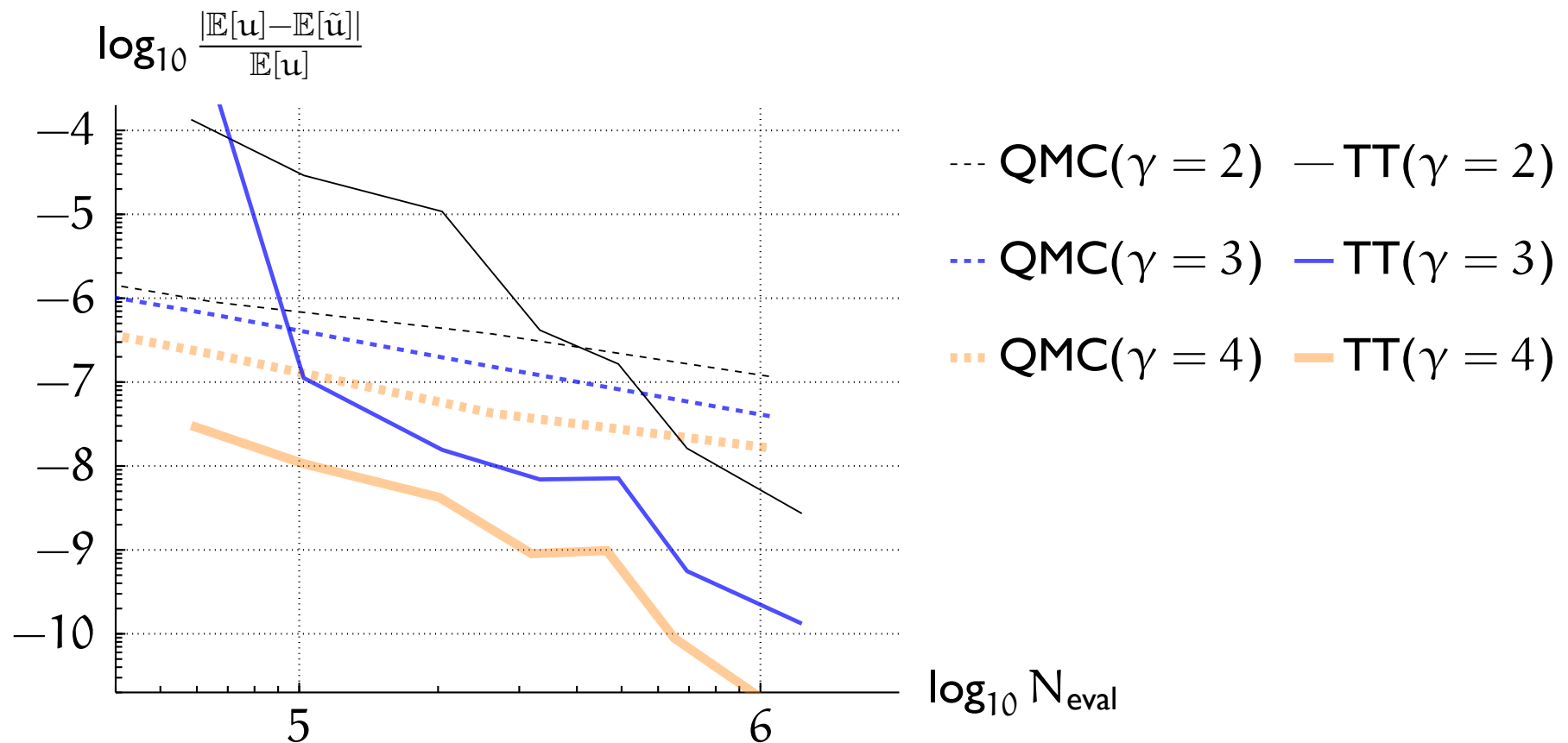
$$-\nabla_x(a(x, \xi)\nabla_x u(x, \xi)) = 1 \quad x \in [0, 1]$$

$$u(x, \xi) = 0 \quad x \in \{0, 1\}$$

$$a(x, \xi) = \exp\left(\sum_{k=1}^d \frac{1}{k^\gamma} \cos(k\pi x) \xi_k\right)$$

- $d \sim 10$ parameters $\xi_k \in [-1, 1]$
- $n = 15$ LG quadrature points per ξ_k
- $n^d = 15^{10}$ PDEs to solve
- **curse of dimensionality**
- apply **tensor formats**

Stochastic PDE

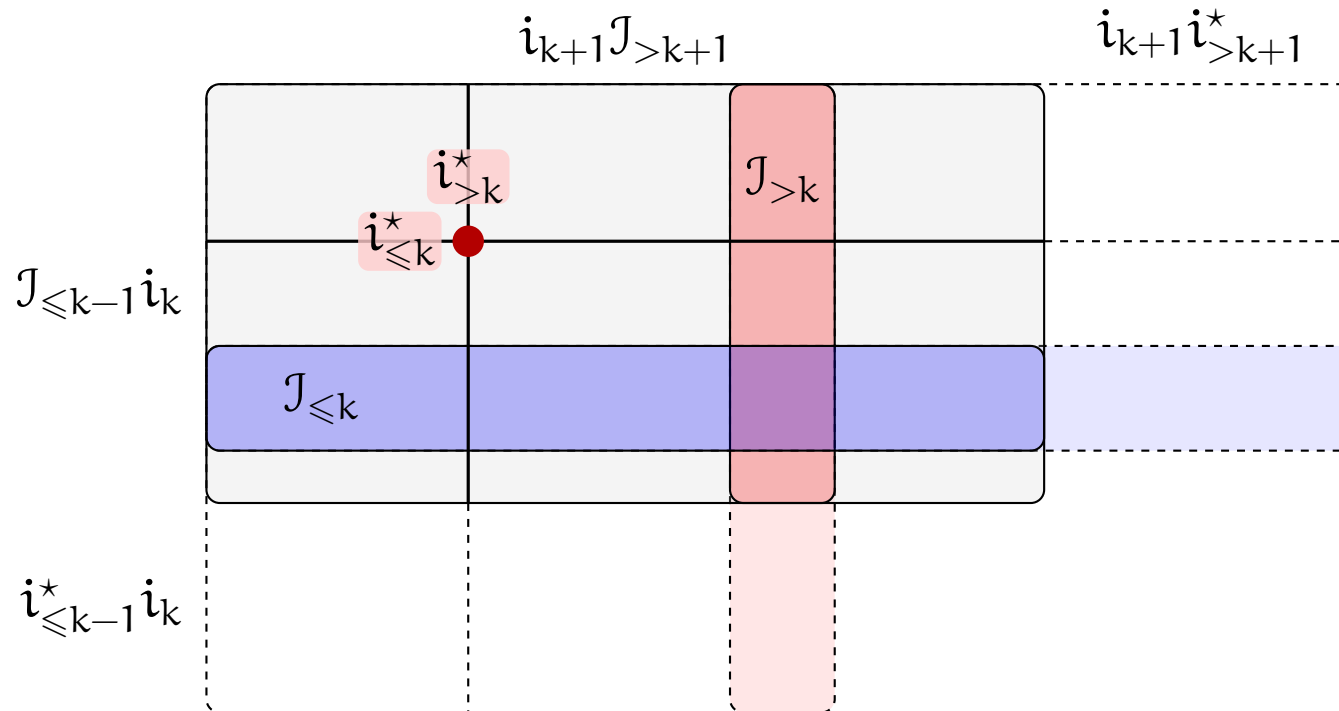
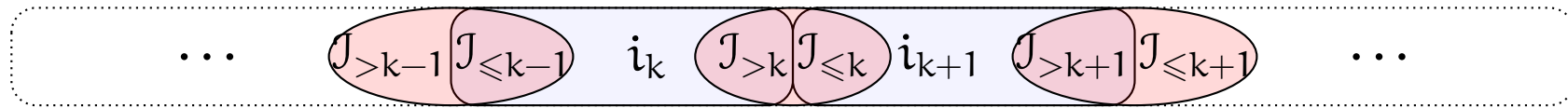


- TT-cross interpolation converges faster than Quasi Monte Carlo
- TT-cross interpolation likes smooth coefficients
- Quasi Monte Carlo still works better when low accuracy is required

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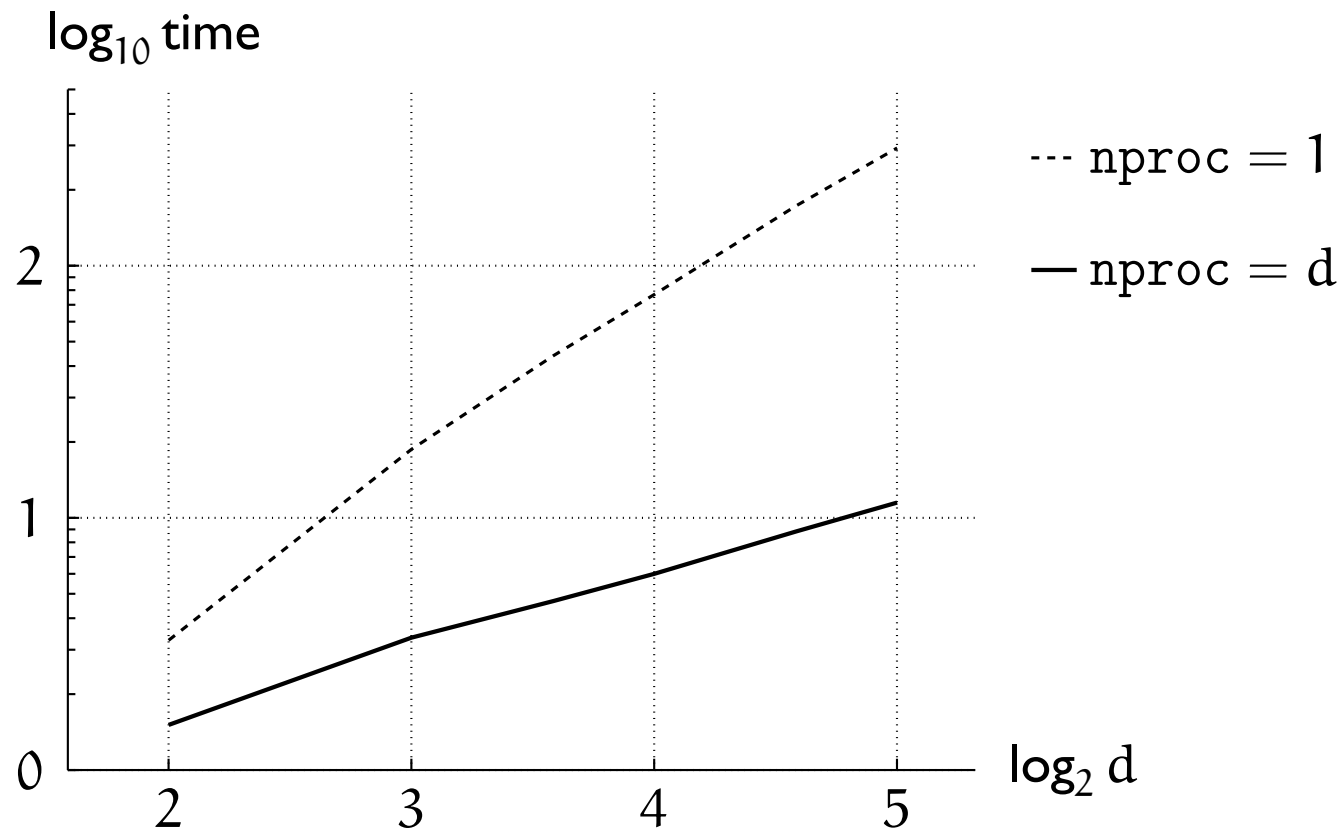
Parallel implementation



Related work

- [[Grasedyck et al, Comput. Visual. Sci. 2015](#)] Parallel random sampling in HT
- [[Etter, SISC 2016](#)] Parallel ALS for solving linear systems

Scalability



- implemented in Fortran+MPI
- sequential code scales quadratically with d
- parallel code scales linearly with d (each element costs $\sim d$)

Conclusion

- tensor interpolation is **accurate** (for maxvol sets)
- tensor interpolation formula **interpolates** (for nested sets)
- tensor interpolation algorithm is fast, **scalable** and reliable

References

- Quasioptimality of maximum-volume cross interpolation of tensors

Linear Algebra and Applications 458:217–244, **2014**

